

# Inference for Probabilistic Logic Programming with Continuous Distributions

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*based on joint work with Steffen Michels and Peter Lucas*



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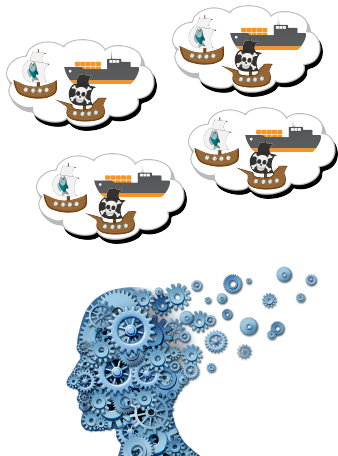
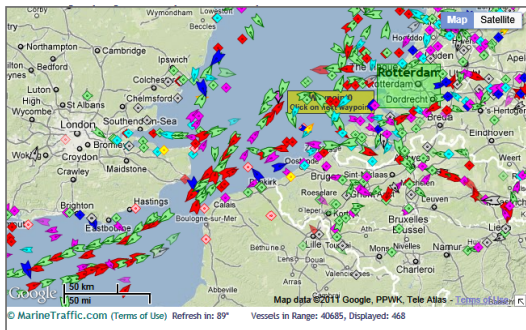


## Motivation: domains with numbers

- Uncertainty over continuous random variables ubiquitous
- E.g. in medicine: the distribution of laboratory test values
  - But also in finance, biology, etc.
- Discretization not always possible during modelling



## Relational domains with numbers



[Michels, S., Velikova, M., Hommersom, A., & Lucas, P. J.F. A decision support model for uncertainty reasoning in safety and security tasks. In SMC2013.]

## Outline

- PLP with linear constraints
- Distributional clauses
  - Sampling
- Iterative hybrid probabilistic model counting
  - Inference using weighted model counting
  - Generalised weighted model counting
  - Iterative refinement of discretisations
  - Experiments
- Conclusions and outlook



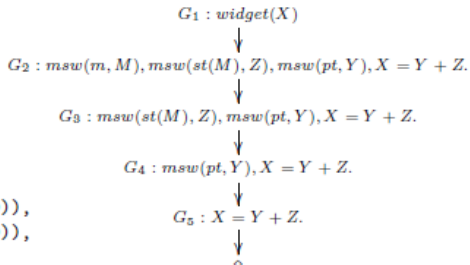


## Representation in PRISM

```
widget(X) :- msw(m, M),
             msw(st(M), Z),
             msw(pt, Y),
             X = Y + Z.

% Ranges of RVs
values(m, [a,b]).
values(st(M), real).
values(pt, real).
% PDFs and PMFs:
:- set_sw(m, [0.3, 0.7]),
   set_sw(st(a), norm(2.0, 1.0)),
   set_sw(st(b), norm(3.0, 1.0)),
   set_sw(pt, norm(0.5, 0.1)).
```

(a) Mixture model program



(b) Symbolic derivation for goal `widget(X)`

[Islam, Muhammad Asiful, C. R. Ramakrishnan, and I. V. Ramakrishnan. "Inference in probabilistic logic programs with continuous random variables." TPLP 2012].

## Main idea

If a derivation with  $m = a$ , then  $X$  is the convolution of  $Y$  and  $Z$ , i.e.

$$X \sim \mathcal{N}(2.5, 1.1)$$

Similarly, if  $m = b$ , then:

$$X \sim \mathcal{N}(3.5, 1.1)$$

Since they are mutually exclusive:

$$p(X) = 0.3\mathcal{N}(2.5, 1.1) + 0.7\mathcal{N}(3.5, 1.1)$$

- Implemented in XSB
- Exact inference
- Restricted language
- Restricted to distributions (stable distributions)



## Distributional clauses

- Distributional clause:

$$h \sim D \leftarrow b_1, \dots, b_n$$

- Meaning: each ground instance of the clause  $(h \sim D \leftarrow b_1, \dots, b_n)\theta$  defines the random variable  $h\theta$  with distribution  $D\theta$  whenever all the  $b_i\theta$  hold, where  $\theta$  is a substitution
- $D$  can be any parameterised distribution, e.g. normal, Gamma, uniform, etc.



## Distributional clauses

$n \sim \text{uniform}([1, 2, 3, 4, 5, 6, 7, 8, 9, 10]).$  (7)

$\text{color}(X) \sim \text{uniform}([\text{grey}, \text{blue}, \text{black}]) \leftarrow \text{material}(X) \sim = \text{metal}.$  (8)

$\text{color}(X) \sim \text{uniform}([\text{black}, \text{brown}]) \leftarrow \text{material}(X) \sim = \text{wood}.$  (9)

$\text{material}(X) \sim \text{finite}([0.3 : \text{wood}, 0.7 : \text{metal}]) \leftarrow n \sim = N, \text{between}(1, N, X).$  (10)

$\text{drawn}(Y) \sim \text{uniform}(L) \leftarrow n \sim = N, \text{findall}(X, \text{between}(1, N, X), L).$  (11)

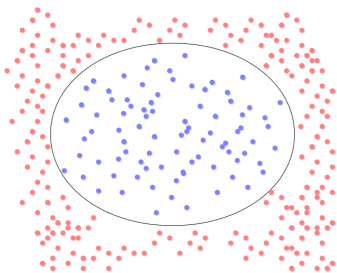
$\text{size}(X) \sim \text{beta}(2, 3) \leftarrow \text{material}(X) \sim = \text{metal}.$  (12)

$\text{size}(X) \sim \text{beta}(4, 2) \leftarrow \text{material}(X) \sim = \text{wood}.$  (13)

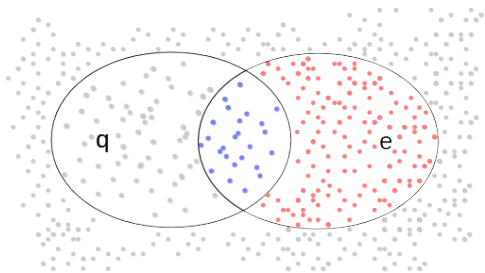
[Davide Nitti, Tinne De Laet, Luc De Raedt. Probabilistic logic programming for hybrid relational domains. Machine Learning, Springer, 2016]



## Sampling: basic idea



$$\tilde{P}(q) = \frac{\#\bullet}{\#\bullet + \#\bullet}$$



$$\tilde{P}(q | e) = \frac{\#\bullet}{\#\bullet + \#\bullet}$$

## Distributional clauses (DC): inference

1: (color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \emptyset$   
↓ 2b on (8) :  
2: (material(2)  $\sim$  metal, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \emptyset$   
↓ 2b on (10) :  
3: (n  $\sim$  N, between(1, N, 2), sample(material(2),  $\mathcal{D}_{\text{material}(2)}$ ), material(2)  $\sim$  metal,  
sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \emptyset$   
↓ 2b on (7) :  
4: (sample(n,  $\mathcal{D}_n$ ), n  $\sim$  N, between(1, N, 2), sample(material(2),  $\mathcal{D}_{\text{material}(2)}$ ),  
material(2)  $\sim$  metal, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \emptyset$   
↓ 3b :  
5: (n  $\sim$  N, between(1, N, 2), sample(material(2),  $\mathcal{D}_{\text{material}(2)}$ ), material(2)  $\sim$  metal,  
sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \{n = 3\}$   
↓ 2a followed by 1a  
6: (sample(material(2),  $\mathcal{D}_{\text{material}(2)}$ ), material(2)  $\sim$  metal, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ),  
color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \{n = 3\}$   
↓ 3b :  
7: (material(2)  $\sim$  metal, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black)  
↓  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \{n = 3, \text{material}(2) = \text{wood}\}$   
8: fail, backtracking to 1  
↓ 2b on (9) :  
9: (material(2)  $\sim$  wood, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black)  
↓  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \{n = 3, \text{material}(2) = \text{wood}\}$   
↓ 2a :  
10: (sample(material(2),  $\mathcal{D}_{\text{material}(2)}$ ), material(2)  $\sim$  metal, sample(color(2),  $\mathcal{D}_{\text{color}(2)}$ ), color(2)  $\sim$  black);  $w_q^{(i)} = 1$ ;  $x^{P(i)} = \{n = 3, \text{material}(2) = \text{wood}\}$



## IHPMC setting

- Distributional clauses, but with fixed distributions

$fails(Comp) \leftarrow \mathbf{FailCause}(Comp, Cause) = true$

$fails(Comp) \leftarrow \mathbf{Temp} > \mathbf{Limit}(Comp)$

$fails(Comp) \leftarrow subcomp(Subcomp, Comp), fails(Subcomp)$

$\mathbf{FailCause}(engine, noFuel) \sim \{0.0002: true, 0.9998: false\}$

$\mathbf{Temp} \sim \Gamma(20.0, 5.0)$

$\mathbf{Limit}(engine) \sim \mathcal{N}(65.0, 5.0)$

$subcomp(fuelPump, engine)$

$\mathbf{Limit}(fuelPump) \sim \mathcal{N}(80.0, 5.0)$

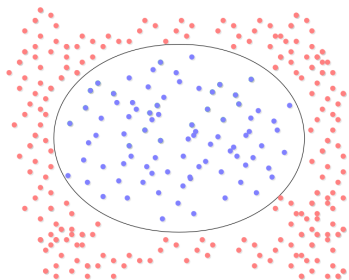
...

- Probability of query event  $q$ , given evidence  $e$ :  $P(q \mid e)$

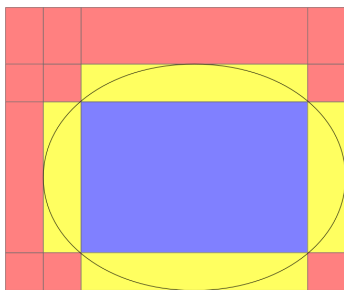
$$P(fails(fuelPump) \mid fails(engine))$$



## IHPMC: basic idea



$$\tilde{P}(q) = \frac{\# \bullet}{\# \bullet + \# \bullet}$$



$$\underline{P}(q) = P(\blacksquare)$$

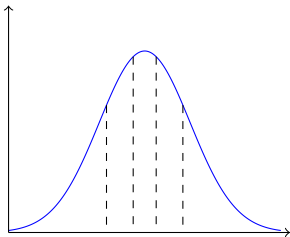
$$\overline{P}(q) = P(\blacksquare) + P(\blacksquare)$$

$$\tilde{P}(q) = P(\blacksquare) + P(\blacksquare)/2 \pm P(\blacksquare)/2$$



## Approximating continuous distributions

- Desired: usage of known PDFs
- Example:  $X \sim \mathcal{N}(3.0, 1.0)$
- Aim: discretisation of PDFs



$$\mathbf{X} \sim \{0.2 : \mathbf{X} < 2.15837876642709, \\ 0.2 : 2.15837876642709 < \mathbf{X} < 2.7466528968642, \dots\}$$

## Generalised distribution semantics

- Sato's distribution semantics
  - $P_f(f_1, f_2, \dots)$  on binary probabilistic facts
  - $h \leftarrow l_1, \dots, l_n, f_1, \dots, f_m$
  - $P_f$  can uniquely be extended to all atoms in rules
- Generalised distribution semantics
  - $P_V(\mathbf{V}_1, \mathbf{V}_2, \dots)$  on random variables with arbitrary ranges
  - $h \leftarrow l_1, \dots, l_n, \varphi_1(\mathbf{V}_1, \mathbf{V}_2, \dots), \dots, \varphi_m(\mathbf{V}_1, \mathbf{V}_2, \dots)$
  - $P_V$  can uniquely be extended to all atoms in rules

[Michels, S., Hommersom, A., Lucas, P. J., & Velikova, M. (2015). A new probabilistic constraint logic programming language based on a generalised distribution semantics. Artificial Intelligence, 2015]



## Credal sets of these distributions

- Most  $P_V$ : no analytic solutions
- Credal sets of probability distributions  $\mathbf{P}$
- $\mathbf{V}_i(X_1, \dots, X_n) \sim \{p_1: \varphi_1, \dots, p_l: \varphi_m\}$  define *non-empty*  $\mathbf{P}$ , e.g.

$$\mathbf{X} \sim \{0.2 : \mathbf{X} < 2, 0.8 : \mathbf{X} \geq 2\}$$

- Clauses extend each distribution in the credal set (e.g.  $q \leftarrow \mathbf{X} > 0$ )
- Exact inference conditions (bounds:  $\min/\max\{P(q) \mid P \in \mathbf{P}\}$ )
  - *finite-support condition* [Sato, 1995]  
(**counterexample**:  $q(X) \leftarrow \mathbf{V}_1 > X, q(X + 1)$ )
  - *finite-dimensional-constraints condition*  
(**counterexample**:  $q \leftarrow \bigvee_{i,j \in \mathbb{N}} i > j \rightarrow \mathbf{V}_i > \mathbf{V}_j$ )
  - *disjoint-events-decidability condition*  
( $e_1 \cap e_2 = \emptyset$  decidable, implementation:  
 $check(\varphi_1 \wedge \varphi_2) = \text{unsat}$ )



## Example (adapted from [Binder et al., 1997])

**Yield**(*apple*)  $\sim$  (a discretized normal)

**Yield**(*banana*)  $\sim$  ...

**Support**(*apple*)  $\sim$  {0.3: *yes*, 0.7: *no*}

**Support**(*banana*)  $\sim$  {0.5: *yes*, 0.5: *no*}

*basic\_price*(*apple*, 250 - 0.007 · **Yield**(*apple*))

*basic\_price*(*banana*, 200 - 0.006 · **Yield**(*banana*))

*price*(*Fruit*, *BPrice* + 50)  $\leftarrow$

*basic\_price*(*Fruit*, *BPrice*), **Support**(*Fruit*) = *yes*

*price*(*Fruit*, *BPrice*)  $\leftarrow$

*basic\_price*(*Fruit*, *BPrice*), **Support**(*Fruit*) = *no*



## Example (adapted from [Binder et al., 1997])

**Max\_price**(*apple*)  $\sim$  (a discretised Gamma)

**Max\_price**(*banana*)  $\sim$  ...

$buy(Fruit) \leftarrow price(Fruit, P), P \leq \mathbf{Max\_price}(Fruit)$

$P(buy(apple)) \approx 0.464 \pm 0.031$

$P(buy(banana)) \approx 0.162 \pm 0.031$

$P(buy(apple) \vee buy(banana)) \approx 0.552 \pm 0.054$



## Inference algorithm: weighted model counting

- Weighted Boolean formula consists of
  - A propositional formula  $\phi$
  - Weights on every literal  $w(l)$
- Weighted model counting (WMC) gives

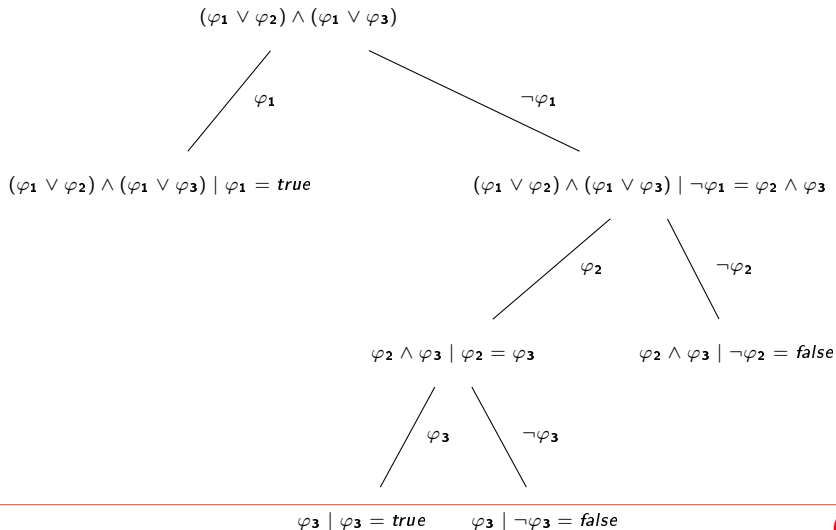
$$weight(\phi) = \sum_{M \models \phi} \prod_{l \in M} w(l)$$

- Any discrete PLP query can be converted to a WMC problem
  - Equivalent formula involving independent random variables only
  - Exploiting local structure  $\Rightarrow$  especially important in PLP
  - Implemented in Problog2

[Fierens, Daan, et al. Inference and learning in probabilistic logic programs using weighted Boolean formulas. TPLP 2015]



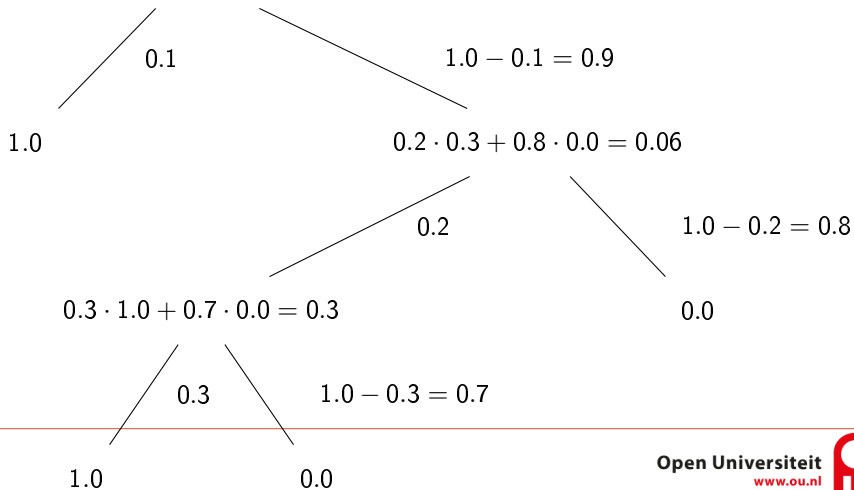
## DPLL example



## DPLL for WMC example

$$P(\varphi_1) = 0.1 \quad P(\varphi_2) = 0.2 \quad P(\varphi_3) = 0.3$$

$$0.1 \cdot 1.0 + 0.9 \cdot 0.06 = 0.154$$





## Inference with credal sets

- Generalised WMC

WMC	GWMC
True/False choices	Choices in definitions
Simplification of CNF	Simplification of constraint
Single probabilities	Probability tuples

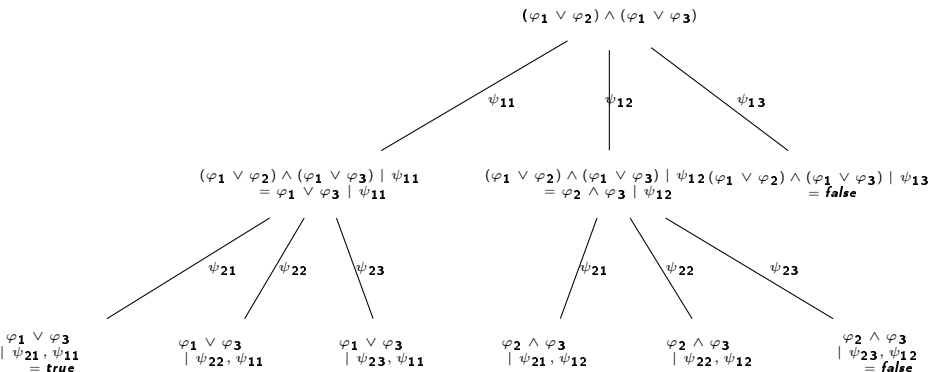
- Same complexity
- Exploitation of additional structure (determinism, ...)

## Generalised WMC example

$$\varphi_1 = \mathbf{V}_1 < 0.75 \quad \varphi_2 = \mathbf{V}_1 < 1.25 \quad \varphi_3 = \mathbf{V}_1 + 0.25 \cdot \mathbf{V}_2 < 1.375$$

$$\mathbf{V}_1 \sim \{0.7: 0 \leq \mathbf{V}_1 \leq 1, 0.2: 1 \leq \mathbf{V}_1 \leq 2, 0.1: 2 \leq \mathbf{V}_1 \leq 3\}$$

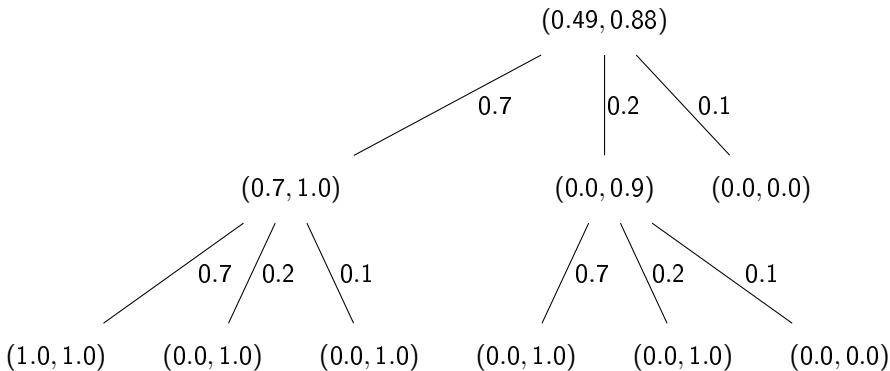
$$\mathbf{V}_2 \sim \{0.7: 0 \leq \mathbf{V}_2 \leq 1, 0.2: 1 \leq \mathbf{V}_2 \leq 2, 0.1: 2 \leq \mathbf{V}_2 \leq 3\}$$



## Generalised WMC example (2)

$$\mathbf{V}_1 \sim \{0.7: 0 \leq \mathbf{V}_1 \leq 1, 0.2: 1 \leq \mathbf{V}_1 \leq 2, 0.1: 2 \leq \mathbf{V}_1 \leq 3\}$$

$$\mathbf{V}_2 \sim \{0.7: 0 \leq \mathbf{V}_2 \leq 1, 0.2: 1 \leq \mathbf{V}_2 \leq 2, 0.1: 2 \leq \mathbf{V}_2 \leq 3\}$$



## Iterative Hybrid Probabilistic Model Counting

- Generalizes the idea above in an *iterative* way
  - Automatic refinement of continuous distributions
  - Constructs a *hybrid probability tree* on the fly
- Main theoretical result:  
**Approximations with arbitrary precision can be computed in finite time!**

For all events  $q$  and  $e$  and every maximal error  $\epsilon$ , IHPMC can in finite time find an approximation such that:

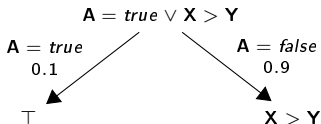
$$P(q | e) - \underline{P}(q | e) \leq \epsilon \text{ and} \\ \overline{P}(q | e) - P(q | e) \leq \epsilon$$

[Steffen Michels, Arjen Hommersom, Peter J. F. Lucas. Approximate Probabilistic Inference with Bounded Error for Hybrid Probabilistic Logic Programming. IJCAI'16]



## Example HPT

### Hybrid Probability Tree (HPT)



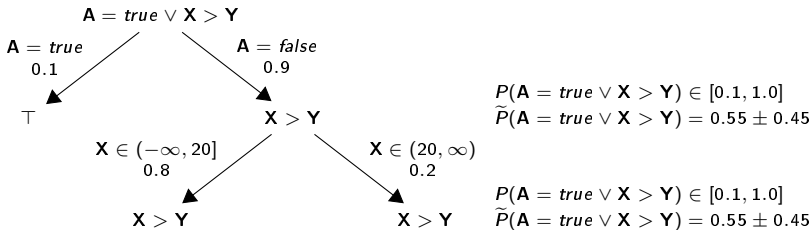
$$P(A = true \vee X > Y) \in [0.1, 1.0]$$

$$\tilde{P}(A = true \vee X > Y) = 0.55 \pm 0.45$$

- Similar to binary WMC
- Exploits logical structure
- Search towards hyperrectangles with high probability

## Example HPT

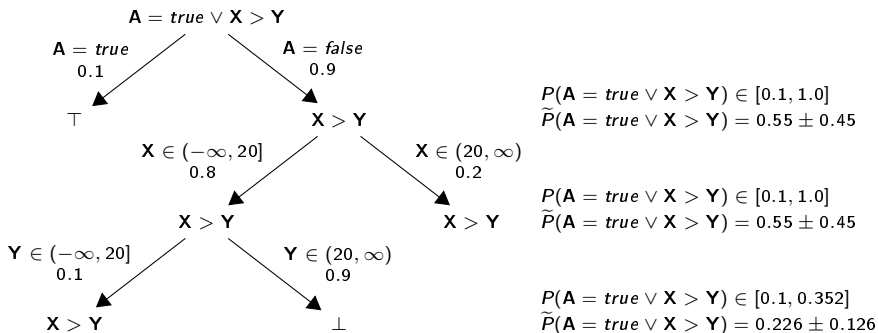
### Hybrid Probability Tree (HPT)



- Similar to binary WMC
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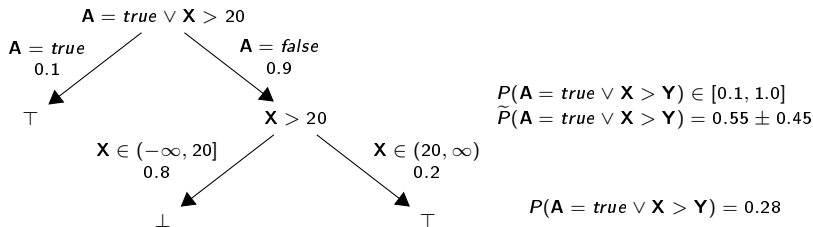
## Example HPT

### Hybrid Probability Tree (HPT)



- Similar to binary WMC
- Exploits logical structure
- Search towards hyperrectangles with high probability

## Special case: one-dimensional constraints



- Equivalent to Hybrid ProbLog
- There exists a finite HPT where all leafs are either  $\top$  or  $\perp$
- Inference is *exact*

[Gutmann, Bernd, Manfred Jaeger, and Luc De Raedt. Extending ProbLog with Continuous Distributions. ILP'10]



## Evaluation

- Diagnosis Problem

**Break**(\_)  $\sim \{p: \text{true}, 1 - p: \text{false}\}$

**Temp**  $\sim \mathcal{N}(20.0, 5.0)$

**Limit**(\_)  $\sim \mathcal{N}(\mu, 5.0)$

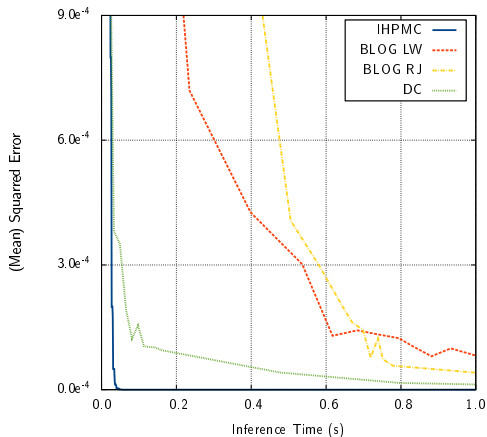
$\text{fails}(i) \leftarrow \mathbf{Break}(i) = \text{true}$

$\text{fails}(i) \leftarrow \mathbf{Temp} > \mathbf{Limit}(i)$

$\text{fails}(i) \leftarrow i \neq 0, \text{fails}(i - 1)$

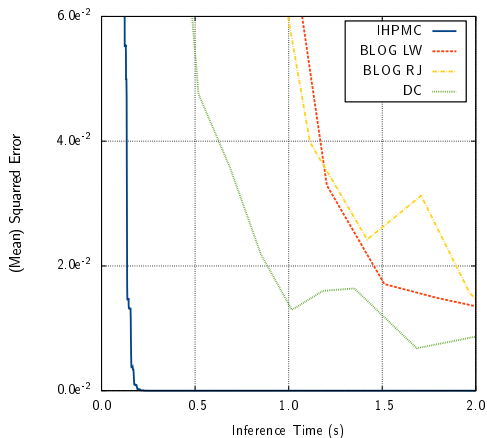
- Comparison with state-of-the-art samplers
  - *BLOG*: Rejection Sampler
  - *BLOG*: Likelihood Weighting Sampler
  - *Distributional Clauses*: Sequential Monte Carlo Sampler

## No evidence



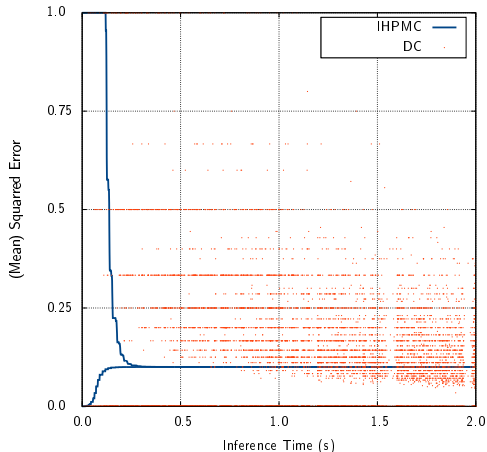
$$P(\text{fails}(9)), \rho = 0.01, \mu = 60.0$$

## Rare observed event



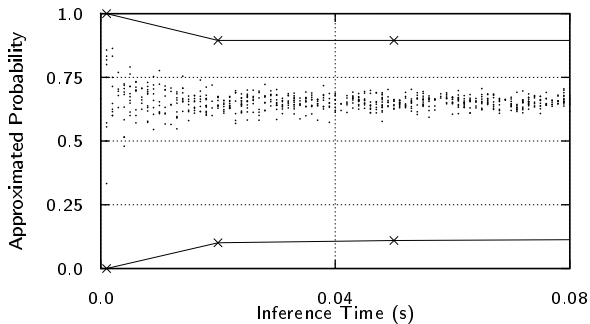
$$P(\text{fails}(9) \mid \text{fails}(0)), \rho = 0.0001, \mu = 60.0$$

## Approximations rare observed event



$$P(\text{fails}(9) \mid \text{fails}(0)), p = 0.0001, \mu = 60.0$$

## When IHPMC fails...



## Summary of inference methods

Method	Exact	Rejection / Importance Sampling	MCMC	IHPMC
Works for	limited number of problems	(virtually) all problems	(virtually) all problems	large class of hybrid problems
Quality guarantee	no error	probabilistic	none	bounded error
Structure-sensitive	yes	no	hand-tailored solution often required	yes
Sensitive to rare evidence	no	yes	no	no

## Conclusions and future work

### Conclusions:

- Nowadays there are good alternatives for inference in hybrid PLPs
- For special cases exact inference possible
- Sampling generic and often performs well
- IHPMC provides alternative to sampling
  - insensitive to rare observed events
  - no hand-tailoring
  - bounded error
  - may fail, **but lets the user know!**
  - Try it: <http://www.steffen-michels.de/ihpmc>

### Possible directions for future research:

- Variational inference: scalable technique for approximate inference
- Conditioning on continuous variables

